

ABSTRACT

Firstly, a template image is created (S501). Then,
an image I^t is photographed (S502). And the sensor output
is acquired (S503). A model view matrix M^t is calculated
5 on the basis of the sensor output (S504). And a correction
matrix ΔM^t is calculated (S505). And the model view matrix
 M^t is corrected employing the calculated correction matrix
 ΔM^t (S506). Then CG is drawn and displayed using the
corrected model view matrix (S507).